Verified Forward Erasure Correction with Coq and VST

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Plan

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- Verifying the Implementation
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Reliable Networking



- How can we ensure network defenses will protect against attackers?
- Attackers may have access to source code, ability to disrupt certain links
- Testing and static analysis not sufficient need to know that defenses work for all possible inputs
- Larger project (Princeton, Cornell, Peraton Labs) formally verify network components written in C and P4
- One particular defense Forward Erasure Correction

Error-Correcting Codes

- Transporting data across network can result in lost packets
- Goal of Forward Erasure Correction add extra parity packets to allow lost packets to be recovered
- Do so with use of an *error-correcting code (ECC)*
- ECCs used in cases when retransmission is expensive or impossible (eg: networks, satellites, etc) and in data storage
- Lots of ECCs exist (Hamming, Reed-Solomon, Convolutional, BCH, etc), most based on fairly sophisticated math
- Correctness is difficult to formally prove
- Erasure code locations of missing packets are known

Project Goals

- Formally verify real-world C implementation of FEC with Coq and the Verified Software Toolchain (VST)
- C code was originally written by Anthony McAuley of Bellcore in early '90s based on algorithm developed by Rabin [Journal of the ACM 1989], McAuley [SIGCOMM 90], and others
- Code has been in active use since
- Verification consists of two very different tasks:
 - 1. Prove that the underlying algorithm is correct (using Coq and Mathematical Components)
 - 2. Prove that the C code implements this algorithm correctly (using Coq and VST)

Coq and VST

- Coq is an interactive theorem prover using a higher-order dependently typed logic
- CompCert (Leroy) optimizing C compiler verified in Coq
- Verified Software Toolchain (Appel) a program logic for C programs (higher-order separation logic) and proof automation tools for verifying C code
- Proved sound wrt CompCert C
- Formal proof that any theorems proved with VST hold of the assembly code generated by CompCert





FEC Setup





- Append *h* extra packets to recover up to *h* lost packets
- Parity packets computed columnwise - we can think of each column as a vector
 - Algorithm is based on Reed-Solomon coding (first invented in 1960s)

Reed-Solomon Overview

- Interpret data as a polynomial over a finite field \circ ie: $(a_0, a_1, \dots, a_{k-1}) \rightarrow a_0 + a_1 x + \dots + a_{k-1} x^{k-1}$
- Evaluate polynomial at *k+h* distinct points in the field
- Equivalently, multiply by Vandermonde matrix
- To make systematic, multiply by row-reduced Vandermonde matrix

$$\begin{bmatrix} a_0 & a_1 & a_2 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 & 1 \\ x_0 & x_1 & x_2 \\ x_0^2 & x_1^2 & x_2^2 \end{bmatrix}$$

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} & a_{15} & a_{16} \\ a_{21} & a_{22} & a_{23} & a_{24} & a_{25} & a_{26} \\ a_{31} & a_{32} & a_{33} & a_{34} & a_{35} & a_{36} \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 & x_1 & x_2 & x_3 \\ 0 & 1 & 0 & x_4 & x_5 & x_6 \\ 0 & 0 & 1 & x_7 & x_8 & x_9 \end{pmatrix}$$

- Simpler than full Reed-Solomon because we don't need to find error locations
- Encoder multiply input by some weight matrix W:

$$P_{h \times c} = W_{h \times k} \cdot D_{k \times c}$$

• What properties does *W* need to allow us to decode?

- First, suppose last *h* data packets are lost, all parities received
- Let D_1 be received data, D_2 be missing data, we have:

$$W = h \left\{ \left[\begin{array}{cc} k - h & h \\ \hline W_1 & W_2 \end{array} \right] \right\}$$



$$P = WD = W_1D_1 + W_2D_2$$
$$D_2 = (W_2)^{-1}(P - W_1D_1)$$

So, we need $(W_2)^{-1}$ (arbitrary $h \times h$ submatrix of W) to be invertible!

- What if some parity packets are lost?
- Let *xh* be number of lost data packets; we must have received at least *xh* parities
- Suppose only the first xh parities were received (P_1):

$$xh \left\{ \begin{pmatrix} W_1 & W_2 \\ W_1 & W_2 \end{pmatrix} \begin{pmatrix} D_1 \\ D_2 \end{pmatrix} = \begin{pmatrix} P_1 \\ P_1 \end{pmatrix} \right\} xh$$
$$P_1 = W_1 D_1 + W_2 D_2$$
$$D_2 = (W_2)^{-1} (P_1 - W_1 D_1)$$

- General case is similar, but W_1 , W_2 , and P_1 may not be contiguous
- We need W₂ to be invertible, where W₂ is any *xh* x *xh* submatrix of W
- In other words, we need every submatrix up to size h x h to be invertible
- Row-reduced Vandermonde matrix has this (strong) property!

matrix
$$V = \begin{pmatrix} \alpha_1^2 & \alpha_2^2 & \dots & \alpha_{h+k}^2 \\ \vdots & \vdots & \vdots & \vdots \\ \alpha_1^{h-1} & \alpha_2^{h-1} & \dots & \alpha_{h+k}^{h-1} \end{pmatrix}$$

 $\begin{bmatrix} 1 & 1 & \dots & 1 \\ \alpha_1 & \alpha_2 & \dots & \alpha_{h+k} \end{bmatrix}$

$$V_{h \times (h+k)} \xrightarrow{\text{Gaussian elim}} \left[I_{h \times h} \mid W_{h \times k} \right]$$

Reed-Solomon Erasure (RSE) Algorithm

• Same as above, but using static weight matrix

- Initialization: create row-reduced Vandermonde matrix (weight matrix)
- Encoder matrix multiplication (P=WD)
- Decoder 2 matrix multiplications and a matrix inversion $((W_2)^{-1}(P_1 W_1 D_1))$

Verification Structure

- 2 very different tasks: prove algorithm is correct and prove C code implements algorithm
- Define *functional model* purely functional version of algorithm written in Gallina using Mathematical Components library (collection of formalized mathematics)
- Can prove properties of functional model completely independent of C program - can be used for other implementations and serves as independent spec
- Prove only that C program implements functional model with VST
- Makes proofs shorter, more modular





- Actually need 2 functional models
- High-level uses uses Mathcomp matrix, ordinal, and polynomial types - abstract and dependently typed
- Low level uses concrete types list(list byte) and similar
 - nontrivial translation
- Correctness properties only use Mathcomp, refinement proof only uses VST

- Standard algorithm in linear algebra to row reduce a matrix over a field
 - transform using row swaps, scalar multiplication, and adding multiples of rows
- Can be used to calculate inverses, determinants, solve systems of linear equations
- In this application used to create weight matrix and invert matrix in decoder

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} & a_{15} & a_{16} \\ a_{21} & a_{22} & a_{23} & a_{24} & a_{25} & a_{26} \\ a_{31} & a_{32} & a_{33} & a_{34} & a_{35} & a_{36} \end{pmatrix} \to \begin{pmatrix} 1 & 0 & 0 & x_1 & x_2 & x_3 \\ 0 & 1 & 0 & x_4 & x_5 & x_6 \\ 0 & 0 & 1 & x_7 & x_8 & x_9 \end{pmatrix}$$



1. Define functional model and prove correctness properties

Definition gaussian elim {m n} (A: 'M[F] (m, n)) := all lc 1 (gauss all steps A (insub 0%N) (insub 0%N)). Gaussian elim Definition find invmx {n} (A: 'M[F] n) := rsubmx (gaussian elim (row mx A 1%:M)). Lemma gaussian finds invmx: forall {n} (A: 'M[F]_(n, n)), A \in unitmx -> find invmx A = invmx A.



2. Define low-level functional model and prove equivalence

Definition lmatrix := list (list byte).

```
Definition gauss_restrict_list m n (mx: lmatrix) :=
all_lc_one_partial m n (gauss_all_steps_list_partial m n mx m) (m-1).
```

```
Lemma gauss_restrict_list_equiv: forall {m n} (mx: lmatrix) (Hmn: m <= n),
wf_lmatrix mx m n ->
lmatrix_to_mx m n (gauss_restrict_list m n mx) =
gaussian_elim_restrict_noop (lmatrix_to_mx m n mx) (le Z_N Hmn).
```



3. Define and prove VST spec using low-level functional model

int fec_matrix_transform (fec_sym * p, fec_sym i_max, fec_sym j_max)

```
Definition fec matrix transform spec :=
 DECLARE fec matrix transform
 WITH gv: globals, m : Z, n : Z, mx : list (list byte), s : val, sh: share
 PRE [ tptr tuchar, tuchar, tuchar]
   PROP (0 < m <= n; n <= Byte.max unsigned; wf lmatrix mx m n;
         strong inv list m n mx; writable share sh)
   PARAMS (s; Vubyte (Byte.repr m); Vubyte (Byte.repr n))
   GLOBALS (qv)
   SEP (FIELD TABLES gv;
        data at sh (tarray tuchar (m * n)) (map Vubyte (flatten mx mx)) s)
 POST [tint]
   PROP()
   RETURN (Vint Int.zero)
   SEP(FIELD TABLES gv;
       data at sh (tarray tuchar (m * n))
          (map Vubyte (flatten mx (gauss restrict list m n mx))) s).
```

Lemma body_fec_matrix_transform : semax_body Vprog Gprogf_fec_matrix_transform fec_matrix_transform_spec.

Verifying the Functional Model

- Mathcomp includes thousands of theorems about matrices, polynomials, rings and fields, etc
- We needed to prove results about constructing finite fields, computable polynomial division, Gaussian elimination, and properties of Vandermonde matrices
- 2 main challenges
 - proving that W₂ in decoder is invertible (need sophisticated properties of Vandermonde matrices)
 - 2. proving that modified Gaussian elimination is correct

- C Code does the following: on column *r*
 - Multiply each row by inverse of r^{th} element
 - Subtract *r*th row from all other rows
 - At end, scalar multiply to make all leading coefficients 1
- This is "restricted" Gaussian Elimination

 only works if all elements in rth column are nonzero!
- C code returns errors if this condition is violated
 - "FEC: swap rows (not done yet!)"
- Suggests that authors were unclear why this was sufficient

$$\begin{pmatrix} a & 0 & b & c \\ 0 & d & e & f \\ 0 & 0 & g & h \\ 0 & 0 & i & j \end{pmatrix} \to \begin{pmatrix} \frac{a}{b} & 0 & 1 & \frac{c}{b} \\ 0 & \frac{d}{e} & 1 & \frac{f}{e} \\ 0 & 0 & 1 & \frac{h}{g} \\ 0 & 0 & 1 & \frac{j}{i} \end{pmatrix} \to \begin{pmatrix} \frac{a}{b} & 0 & 0 & \frac{c}{b} - \frac{h}{g} \\ 0 & \frac{d}{e} & 0 & \frac{f}{e} - \frac{h}{g} \\ 0 & 0 & 1 & \frac{h}{g} \\ 0 & 0 & 0 & \frac{j}{i} - \frac{h}{g} \end{pmatrix}$$

When does the rth step succeed?

- Assume that first r-1 steps succeeded
- Upper left submatrix is diagonal with nonzeroes along diagonal
- All other entries in first r columns zero
- Want all A_{k,r} != 0

For $0 \le k < r$, $C_k^r =$ submatrix including rows $0 \dots r - 1$ and columns $0 \dots r$ except k C_k^r is invertible iff $A_{k,r} \ne 0$

(<i>C</i>	\mathcal{P}_{k}^{r}					
	$A_{0,0}$	0		0	0	0		0	$A_{0,r}$		$A_{0,n-1}$
	0	$A_{1,1}$		0	0	0		0	$A_{1,r}$		$A_{1,n-1}$
	:	÷	۰.	÷	÷	÷	·	:	:	·	÷
	0	0		0	$A_{k,k}$	0		0	$A_{k,r}$		$A_{k,n-1}$
	:	÷	·	÷	÷	÷	·	:	:	·	÷
	0	0		0	0	0		$A_{r-1,r-1}$	$A_{r-1,r}$		$A_{r-1,n-1}$
	0	0		0	0	0		0	$A_{r,r}$		$A_{r,n-1}$
	:	:	۰.	÷	÷	:	·	÷	÷	·	÷
	0	0		0	0	0		0	$A_{m-1,r}$		$A_{m-1,n-1}$

When does the rth step succeed?

- Assume that first r-1 steps succeeded
- Upper left submatrix is diagonal with nonzeroes along diagonal
- All other entries in first r columns zero
- Want all A_{k,r} != 0

For $k \ge r$, $R_k^r =$ submatrix including columns $0 \dots r$ and rows $0 \dots r - 1$ and k R_k^r is invertible iff $A_{k,r} \ne 0$

			R_k^r			
$A_{0,0}$	0		0	$A_{0,r}$		$A_{0,n-1}$
0	$A_{1,1}$		0	$A_{1,r}$		$A_{1,n-1}$
:	:	·	:	÷	·	÷
0	0		$A_{r-1,r-1}$	$A_{r-1,r}$		$A_{r-1,n-1}$
0	0		0	$A_{r,r}$		$A_{r,n-1}$
:	:	·	:	:	۰.	÷
0	0		0	$A_{k,r}$		$A_{k,n-1}$
•	÷	·.	÷	÷	·	÷
0	0		0	$A_{m-1,r}$		$A_{m-1,n-1}$

 r^{th} step succeeds iff

 C_k^r is invertible for $0 \le k < r$ and

 R_k^r is invertible for $r \le k < m$

We call this condition r - strongly invertible.

The whole algorithm succeeds iff A is x -strongly invertible for $0 \le x < m$.

emma gauss one step restrict equiv iff:		
<pre>forall {m n} (A: 'M[F]_(m, n)) (r: 'I_m)</pre>	(Hmn: m	<= n),
gauss_invar A r r ->		
gauss_one_step_restrict A r Hmn =		
Some((gauss_one_step A r (widen_ord Hmn	r)).1)	<->
r_strong_inv A Hmn r.		

Theorem gaussian elim equiv:		
<pre>forall {m n} (A: 'M[F]_(m, n))</pre>	(Hmn: m <= n)	(Hm: 0 < m),
strong_inv A Hm Hmn <->		
<pre>gaussian_elim_restrict A Hmn =</pre>	Some(gaussian	elim A).

- Strong invertibility is difficult to satisfy in general (requires m² specific submatrices to be invertible)
- But the matrices in this application are strongly invertible (this is not trivial to show)
- Result formal proof that simpler algorithm suffices in this instance
- Shows why this optimization/mistake is correct

Verifying the Implementation

- C code relatively challenging to verify
 - Originally written over 20 years ago
 - Code does clever and not-so-clever things
 - Not written in ways particularly conducive to verification
 - Documentation is very sparse
- Code is verified exactly as written, except that 1 macro was turned into function
- Found 1 bug used undefined behavior

Verifying the Implementation - Challenges

- Matrices are represented many different ways in memory
 - Pointer to elements, 2D global array, 2D local array (partially filled), unsigned char**
 - Sometimes rows are reversed (for unknown reasons), sometimes not
 - Need lemmas to convert between 1D arrays, 2D arrays, pointers, etc
- Decoder is long and complex uses about 30 local variables, many nested loops
 - VST becomes very slow and requires significant proof engineering to make verification feasible
- Uses (inconsistent) mix of array indexing and pointer arithmetic
 - Requires lemmas and tactics to relate these memory addresses

```
Lemma data_at_2darray_concat : forall sh t n m (al : list (list (reptype t))) p,
Zlength al = n ->
Forall (fun l => Zlength l = m) al ->
complete_legal_cosu_type t = true ->
data_at sh (tarray (tarray t m) n) al p
= data_at sh (tarray t (n * m)) (concat al) p.
```



Correctness Theorem (Low Level)

```
Theorem decoder list correct: forall k c h xh (data packets : list (list byte)).
  (parities : list (option (list byte))) (stats : list byte) (lens : list Z) (parbound: Z),
 0 < k <= fec n - 1 - fec max h ->
 0 < C ->
 0 < h <= fec max h ->
                                                                              Bounds and length info
 xh \leq h ->
 xh \leq k \rightarrow
 0 <= parbound <= h ->
 Zlength (filter (fun x => Z.eq dec (Byte.signed x) 1) stats) = xh ->
 Zlength (filter isSome (sublist 0 parbound parities)) = xh ->
 Zlength parities = h ->
 Zlength stats = k \rightarrow
 Zlength packets = k \rightarrow
 Zlength data = k \rightarrow
 Zlength lens = k \rightarrow
          i, 0 <= i < k -> Znth i lens = Zlength (Znth i data))
                                                                         The lens array is correct
                         -> Byte.signed (Znth i stats) <> 1%Z -> Znth i packets = Znth i data) -
               <=
                     <
                          parities -> 2 (endth l = c)
                                                                                  are correct
                                                                were produced by the encoder
                                              Received naritie
                               uata ->
 decoder list k c packets parities stats lens parbound = data.
                                                                      Decoder recovers original data
```

Bug in Implementation

- In Gaussian elimination, have the code shown in 2 separate places
- i ranges from 0 to i_max, p is pointer to input matrix
- When i=0, m points to p-1
- The comparison n > m is undefined behavior (in C11, even the definition of m is undefined behavior)
- VST will not let us prove this program correct without modifying it

```
q = (p + (i * j_max) + j_max - 1);
m = q - j_max;
for (n = q; n > m; n--) {
//loop body
```

}

Related Work - Network Function Verification

VigNAT [Zaostrovnykh et al., SIGCOMM 2017]: formally verified NAT using symbolic execution and Verifast (semi-automated separation logic tool)

Vigor [Zaostrovnykh et al., SOSP 2019]: extend VigNAT to handle other network functions (load balancer, firewall, etc) and make verification fully automatic

Gravel [Zhang et al., NSDI 2020]: use symbolic execution and SMT solvers to verify middlebox-specific properties of Click elements in C++

All of these efforts are more automatic, but cannot handle FEC - allow only restricted uses of state, do not allow unbounded loops, cannot handle sophisticated mathematical reasoning

Related Work - Formalization of Coding Theory

In **Coq** [Affeldt et al., Journal of Automated Reasoning 2020 and others]: library of formalized coding theory, including Hamming, Reed-Solomon, BCH, and (acyclic) LDPC codes

In **Lean** [Hagiwara et al., ISITA 2015 and Kong et al., ISITA 2018]: formalized Hamming and Insertion-Deletion codes and results about Levenstein distance

In **ACL2** [Nasser et al., Journal of Electronic Testing 2020]: verified Hamming and convolutional codes against a particular memory model

Conclusion and Future Work

- Core FEC code is fully verified
- Code is at

https://github.com/verified-network-toolchain/Verified-FEC

- Remaining code that handles buffer and packet management (calls core FEC code)
- Possible future work implement incremental FEC encoding and decoding at line rate on an FPGA, verify correctness according to same functional model



Questions?

Thanks for listening!